

Spiral 2-9

Tri-State Gates
Memories
DMA

Learning Outcomes

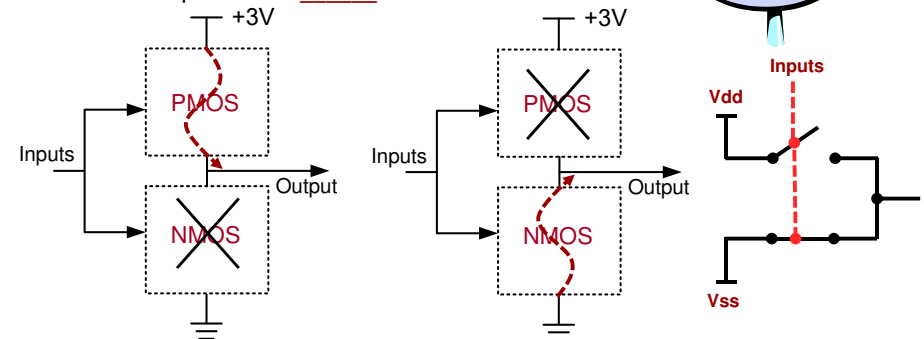
- I understand how a tri-state works and the rules for using them to share a bus
- I understand how SRAM and DRAM cells perform reads and writes
- I understand the pros and cons of SRAM and DRAM
- I understand how modern memories optimize sequential access
- I know what a DMA engine is and why it is used
- I understand the difference between big- and little-endian byte ordering and the problems that might arise when transferring between different orderings

TRI-STATE GATES

Typical Logic Gate

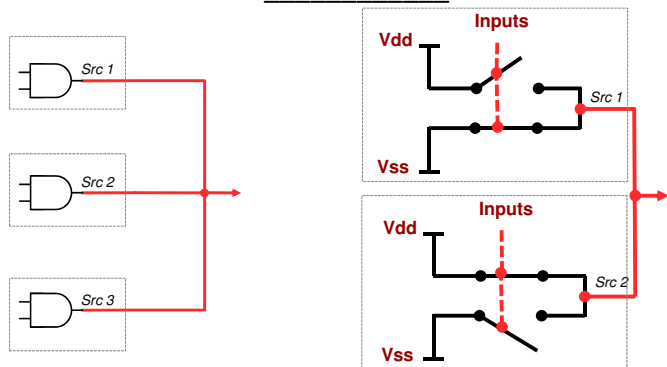
- Gates can output two values: 0 & 1
 - Logic '1' (Vdd = 3V or 5V), or Logic '0' (Vss = GND)
 - But they are ALWAYS _____!!!
- Analogy: a sink faucet
 - 2 possibilities: Hot ('1') or Cold ('0')
- In a real circuit, inputs cause _____ a pathway from output to VDD _____ VSS

Hot Water = _____
Cold Water = _____
(Strapped together so always one type of water coming out)



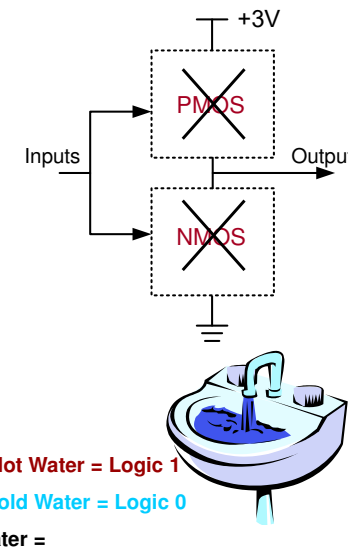
Output Connections

- Can we connect the output of two logic gates together?
- _____! Possible _____ (static, low-resistance pathway from Vdd to GND)
- We call this situation "bus _____"



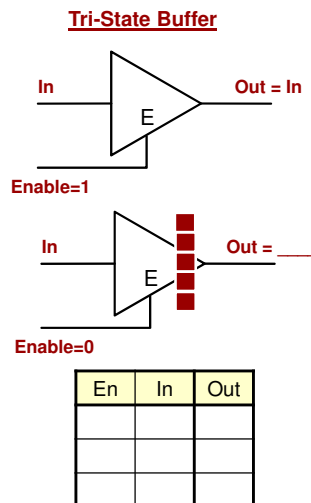
Tri-State Buffers

- Normal digital gates can output two values: 0 & 1
 1. Logic 0 = 0 volts
 2. Logic 1 = 5 volts
- Tristate buffers can output a third value:
 3. _____ = "Floating"
(no connection to any voltage source...infinite resistance)
- Analogy: a sink faucet
 - 3 possibilities:
 - 1.) Hot water,
 - 2.) Cold water,
 - 3.) NO water



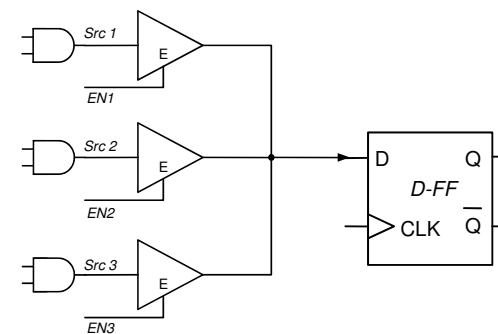
Tri-State Buffers

- Tri-state buffers have an extra _____ input
- When disabled, output is said to be at high impedance (a.k.a. Z)
 - High Impedance is equivalent to no connection (i.e. floating output) or an infinite resistance
 - It's like a brick wall between the output and any connection to source
- When enabled, normal buffer



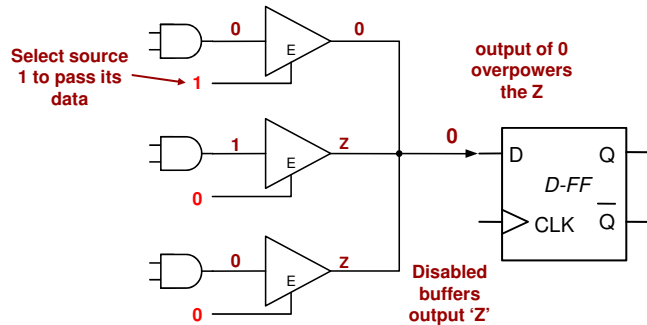
Tri-State Buffers

- We use tri-state buffers to share one output amongst several sources
- Rule: Only _____ at a time



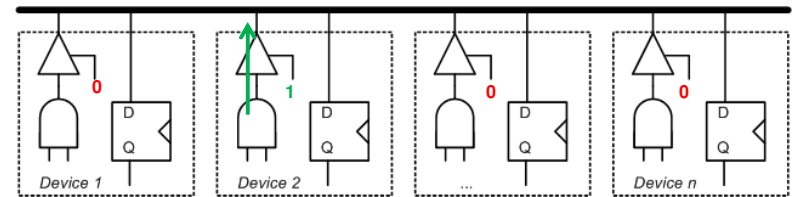
Tri-State Buffers

- We use tri-state buffers to share one output amongst several sources
- When 1 buffer enabled, its output overpowers the Z's (no connection) from the other gates



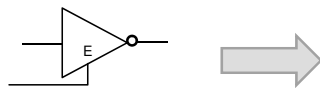
Bidirectional Bus

- ___ transmitter
- ___ receivers
- Each device can send (though _____) or receive



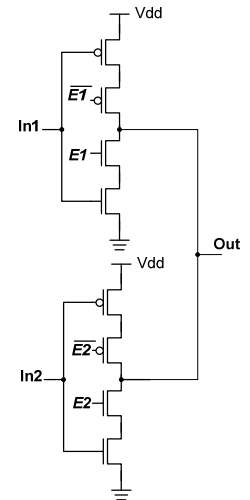
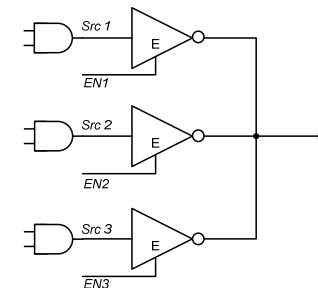
Tri-State Cell Implementation

- To implement we simply add a pair of inner transistors that can BOTH be turned off
 - This would isolate the output from any Vdd or GND connection



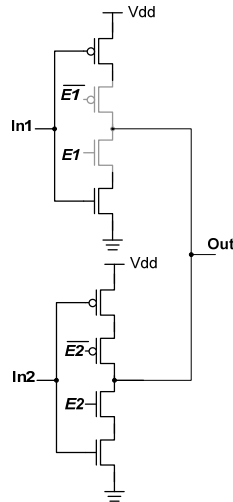
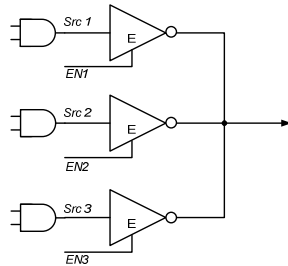
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Tri-State Cell Implementation

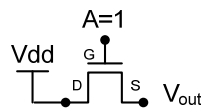
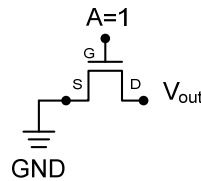
- If $E1 = 0$ then the upper tri-state will isolate the output from any Vdd/GND connection
- If $E2 = 1$ then the lower tri-state acts as a normal inverter
- If both $E1=0, E2=0$ then the output is floating ($Z = \text{high impedance}$)



TRANSMISSION GATE & PASS TRANSISTORS

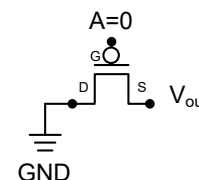
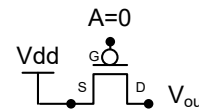
Why NMOS Pass Weak 1s

- We've said NMOS are:
 - Pass a strong 0 but a weak 1
- Let's explore why
 - In the first case one side is tied to GND and thus is the _____ (_____ side is the source)
 - $V_{gs} = V_{dd}$ and transistor will stay on no matter what the drain voltage is (eventually V_d will equal 0)
 - In the second case one side is tied to Vdd and thus the other terminal is the _____ (source is the lower voltage terminal)
 - As the source node charges up eventually it will reach _____ but at that point $V_{gs} = \text{_____}$
 - Recall to stay on the transistor must have _____.
 - So the transistor will turn off and not allow the source to charge all the way to Vdd



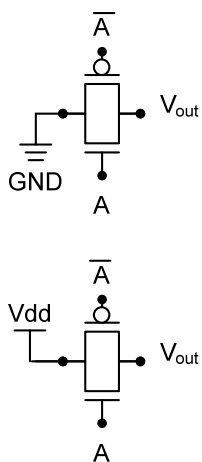
Why PMOS Pass Weak 0s

- We've said PMOS are:
 - Pass a strong 1 but a weak 0
- For similar reasons as on the previous slide when we try to pass a 0 through a PMOS transistor the transistor will turn off when _____
 - This prevents the PMOS from passing a strong 0



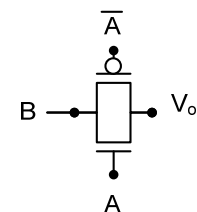
Transmission Gates

- Well if one is good at passing 0's and one is good at passing 1's why not use _____
- A Transmission gate puts a PMOS and NMOS transistors in _____
 - Depending on the input voltage at the _____ either the NMOS or PMOS can pull the drain up/down to that voltage
 - Use _____ inputs at each gate to ensure only one transistor is on



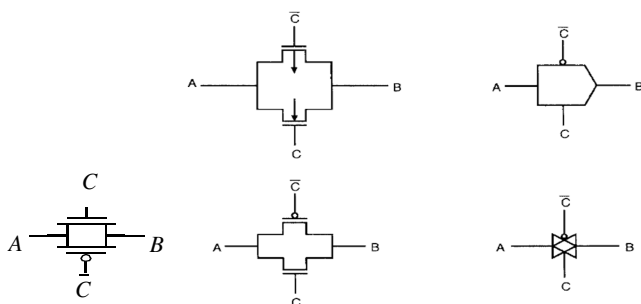
Transmission Gates

- We can even connect the source to some other signal rather than a constant voltage
- In the example to the right, if $A = 1$ ($A' = 0$) then _____
- This gate produces
 - _____ when $A=1$ (_____)
 - _____ when $A=0$



Transmission Gate Symbols

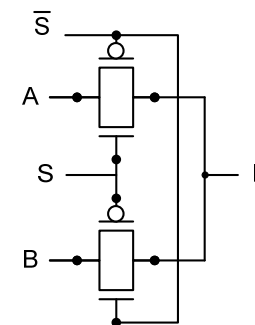
- The CMOS TG operates as a bidirectional switch between nodes A and B, which is controlled by signal C



Different representations (symbols) of the CMOS TGs

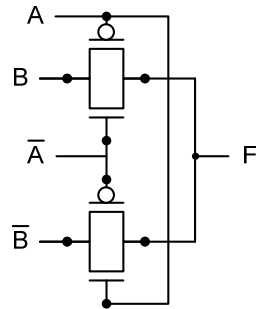
More Transmission Gates

- By making complementary cases of transmission gates we can build some useful structures
- What is this structure?



More Transmission Gates

- What is this structure?

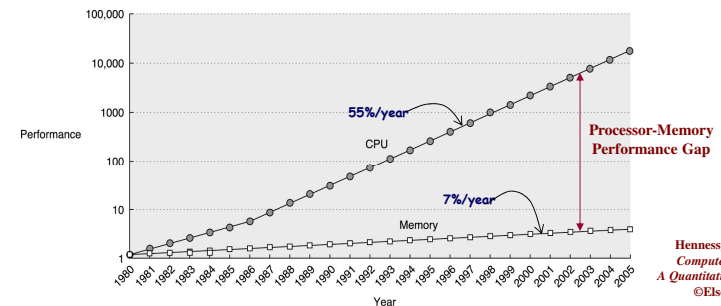


MEMORY

MEMORY TECHNOLOGIES

The Memory Wall

- Problem: The Memory Wall
 - Processor speeds have been increasing _____ than memory access speeds (Memory technology targets density rather than speed)
 - Large memories yield large address decode and access times
 - Main memory is physically located on separate chips and inter-chip signals have much higher propagation delay than intra-chip signals



Improving Memory Performance

- Possibilities for improvement
 - Technology
 - Can we improve our transistor-level design to create faster RAMs
 - Can we integrate memories on the same chip as our processing logic
 - Architectural
 - Can we organize memory in a more efficient manner (this is our focus)

DRAM & SRAM

Memory Technology

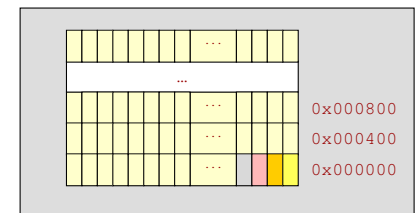
- Static RAM (SRAM)
 - Will retain values _____ (as long as _____)
 - Stored bit is _____ “remembered” (driven and regenerated by circuitry)
- Dynamic RAM (DRAM)
 - Will lose values if not _____
 - Stored bit is _____ “remembered” and needs to be regenerated by external circuitry

Memory Array

- Logical View = 1D array of rows (words)
 - Already this is 2D because each word is 32-bits (i.e. 32 columns)
- Physical View = 2D array of rows and columns
 - Each row may contain 1000’s of columns (bits) though we have to access at least 8- (and often 16-, 32-, or 64-) bits at a time

C8004DB2	0x000c
89AB97CD	0x0008
AB4982FE	0x0004
123489AB	0x0000

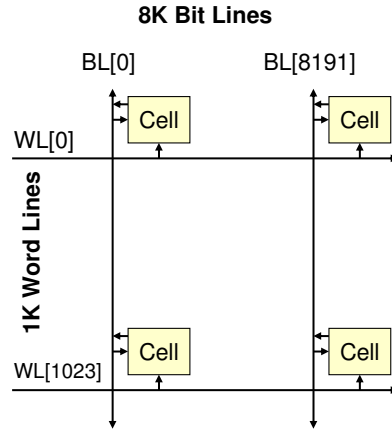
1D Logical View
(Each row is a single word = 32-bits)



2D Physical View
(e.g. a row is 1KB = 8Kb)

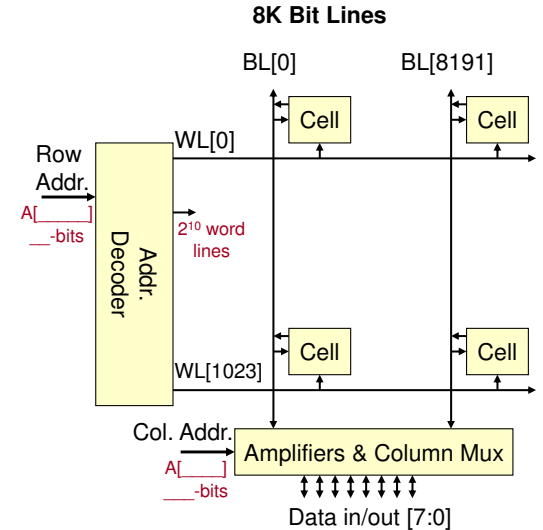
1Mx8 Memory Array Layout

- Start with array of cells that can each store 1-bit
- 1 MB = 8 Mbit = 2^{23} total cells
- This can be broken into a 2D array of cells (_____)
- Each row connects to a WL = _____ which selects that row
- Each column connects to a BL = _____ for read/write data



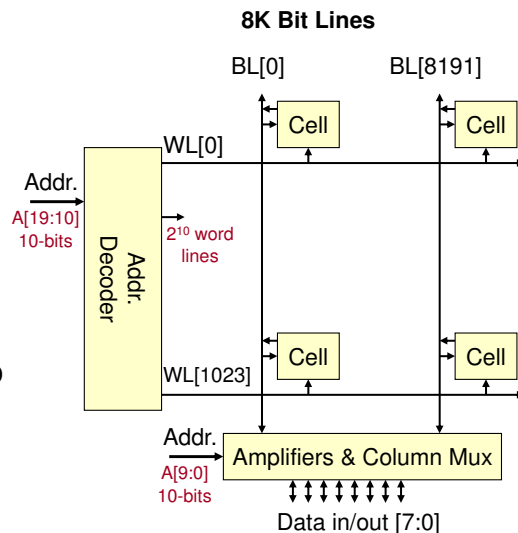
Row and Column Address

- For 1MB we need _____ address bits
- 10 upper address bits can select one of the 1024 rows
- Suppose we always want to read/write an 8-bits (byte), then we will group each set of 8-bits into 1024 byte columns ($1024 * 8 = 8K$)
- 10 _____ address bits will select the _____



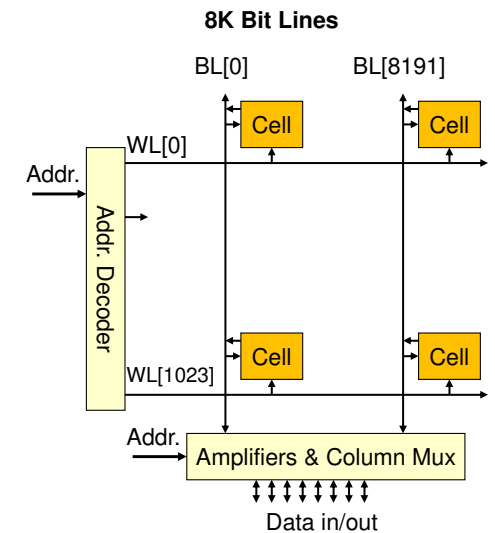
Periphery Logic

- Address decoders selects one row based on the input address number
- Bit lines are bidirectional lines for reading (output) or writing (input)
- Column multiplexers use the address bits to select the right set of 8-bits from the 8K bit lines



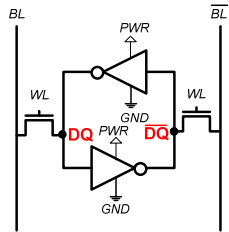
Memory Technologies

- Memory technologies share the same layout but differ in their cell implementation
- Static RAM (SRAM)
 - Will retain values indefinitely (as long as power is on)
 - When read, the stored bit is _____ driven onto the bit lines
- Dynamic RAM (DRAM)
 - Will lose values if not refreshed periodically
 - When read, the stored bit _____ pulls the bit line voltage up or down slightly and needs to be _____

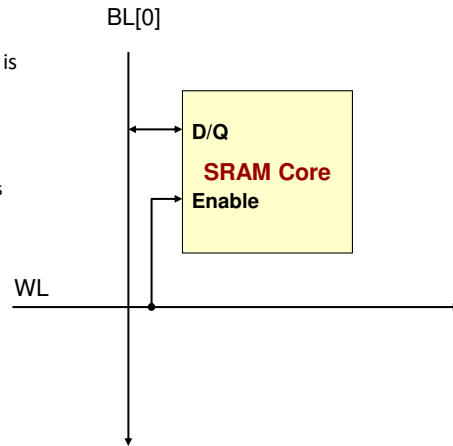


SRAM Cell

- Each memory cell requires _____ **transistors**
- Each cell consists of a _____ is made from cross connected inverters which have active connections to PWR and GND.
 - Thus, the signal is _____ and _____ as long as power is supplied

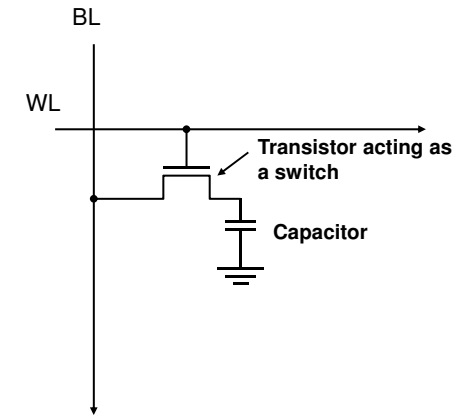


SRAM core implementation



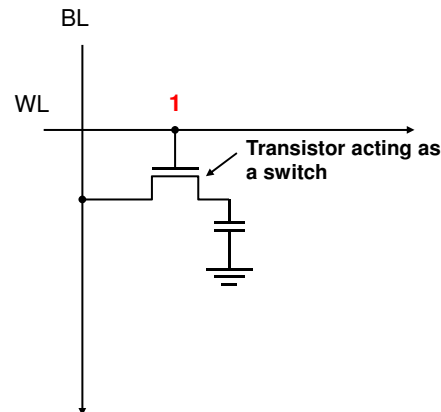
DRAM Cell

- Bit is stored on a capacitor and requires only _____ **transistor and a**



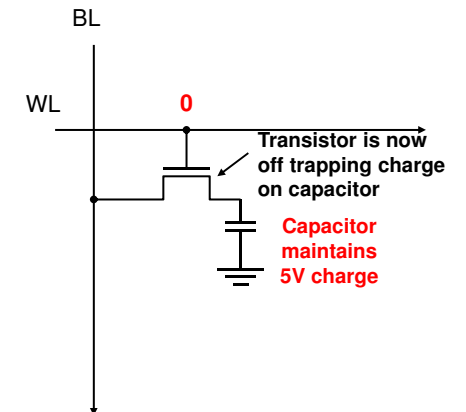
DRAM Cell

- Bit is stored on a capacitor and requires only **1 transistor**
- **Write**
 - WL=1 connects the capacitor to the BL which is driven to 1 or 0 and _____ capacitor based on the BL value



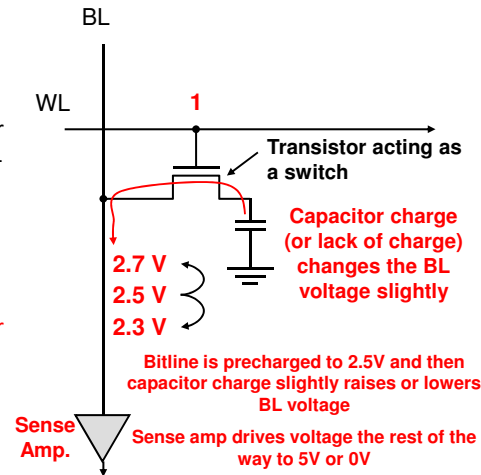
DRAM Cell

- Bit is stored on a capacitor and requires only **1 transistor**
- **Write**
 - WL=1 connects the capacitor to the BL which is driven to 1 or 0 and charges/discharges capacitor based on the BL value
- With WL=0 transistor is closed and value stored on the capacitor



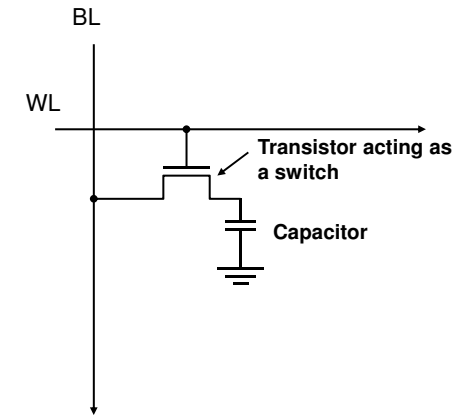
DRAM Cell

- Bit is stored on a capacitor and requires only **1 transistor**
- Write
 - WL=1 connects the capacitor to the BL which is driven to 1 or 0 and charges/discharges capacitor based on the BL value
- Read
 - BL is precharged to 2.5 V
 - WL=1 connects the capacitor to the BL allowing charge on capacitor to change the voltage on the BL



DRAM Issues

- _____
 - Charge is _____ when capacitor value is _____
 - Need to write whatever is _____
- _____ Current
 - Charge slowly _____ the cap.
 - Value must be _____ periodically



SRAM vs. DRAM Summary

- | | |
|--|--|
| <ul style="list-style-type: none"> • SRAM <ul style="list-style-type: none"> – _____ because bit lines are actively driven by the D-Latch – _____, simpler interface due to lack of refresh – _____ for each cell which means less memory per chip – Used for _____ where _____ where speed/latency is key | <ul style="list-style-type: none"> • DRAM <ul style="list-style-type: none"> – _____ because passive value (charge on cap.) drives BL – _____ due to refresh cycles – _____ means much greater density of cells and thus large memories – Used for _____ memory where density is key |
|--|--|

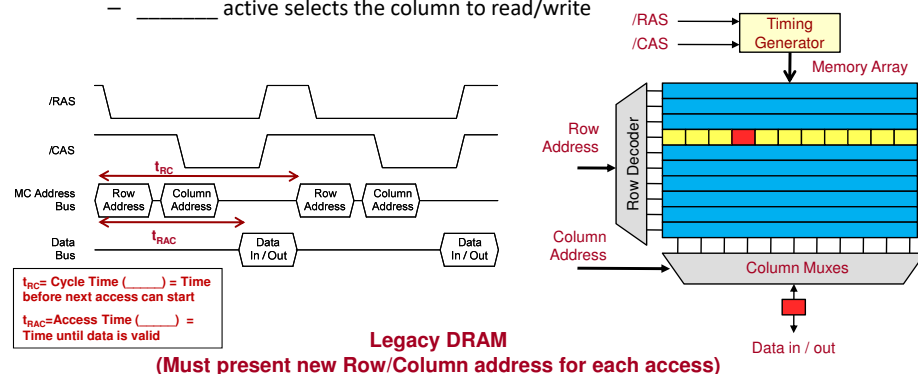
MEMORY ARCHITECTURES

Implications of Memory Technology

- Memory latency of a single access using current DRAM technology will be slow
- We must improve bandwidth
 - Idea 1: Access _____ than just a _____ word at a time
 - Technology: EDO, SDRAM, etc.
 - Idea 2: Increase number of accesses serviced _____
 - Technology: _____

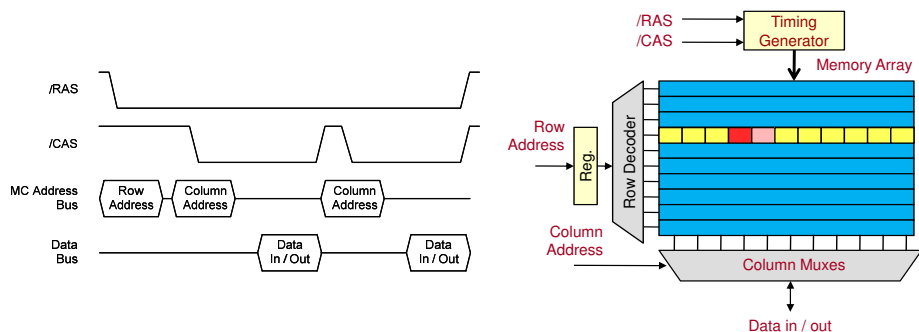
Legacy DRAM Timing

- Can have only a single access “in-flight” at once
- Memory controller must send row and column address portions for each access
 - _____ active holds the row open for reading/writing
 - _____ active selects the column to read/write



Fast Page Mode DRAM Timing

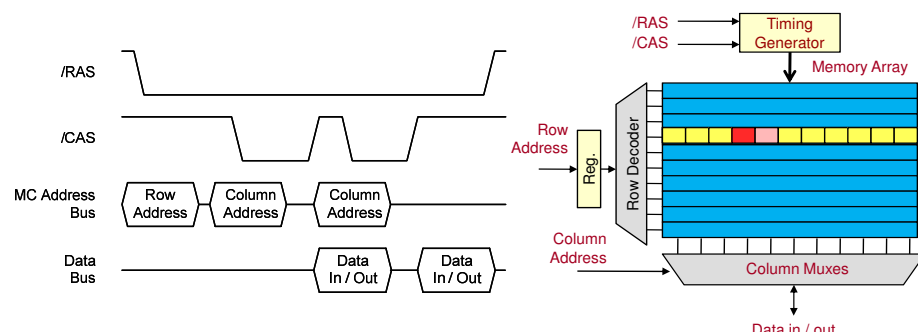
- Can provide multiple column addresses with only one row address



Fast Page Mode
(Future address that fall in same row can pull data from the latched row)

EDO DRAM Timing

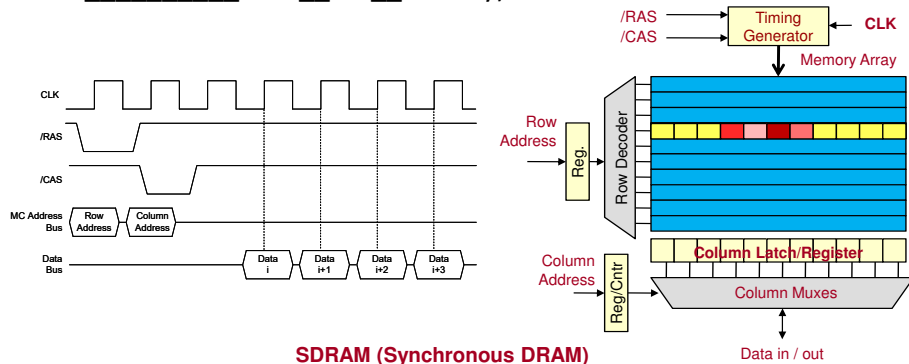
- Similar to FPM but overlaps data i with column address i+1



EDO (Extended Data Out)
Column address i+1 is sent while data i is being transferred on the bus

Synchronous DRAM Timing

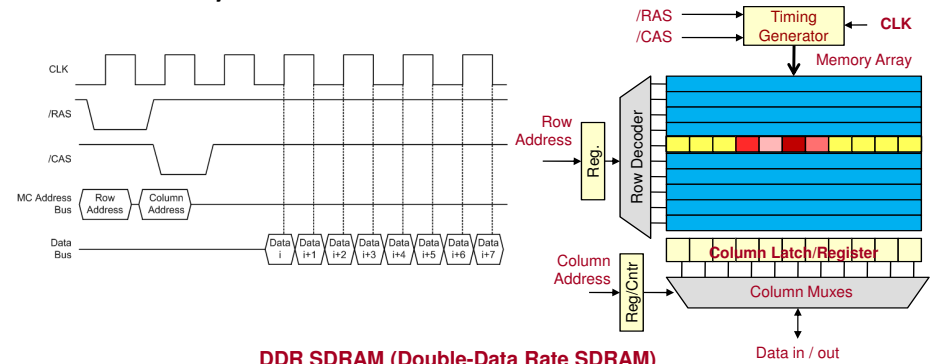
- Registers the column address and automatically increments it, accessing n sequential data words in n successive clocks called _____ ... $n = __$ or $__$ usually)



SDRAM (Synchronous DRAM)
Addition of clock signal. Will get up to 'n' consecutive words in the next 'n' clocks after column address is sent

DDR SDRAM Timing

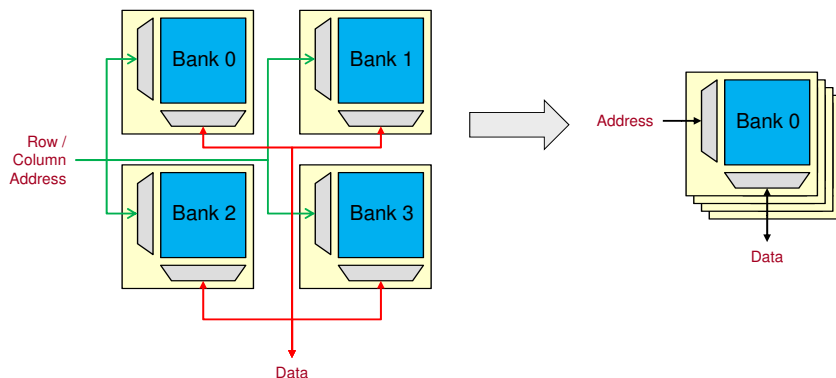
- Double data rate access data every _____ clock cycle



DDR SDRAM (Double-Data Rate SDRAM)
Addition of clock signal. Will get up to '2n' consecutive words in the next 'n' clocks after column address is sent

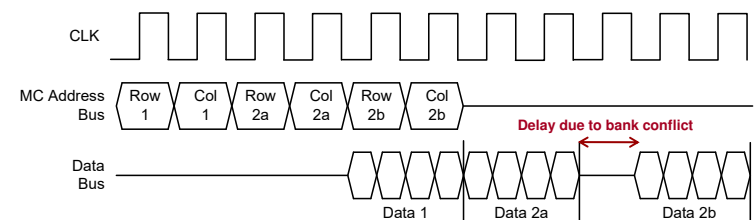
Banking

- Divide memory into "banks" duplicating row/column decoder and other peripheral logic to create independent memory arrays that can access data in parallel
 - uses a portion of the address to determine which bank to access



Bank Access Timing

- Consecutive accesses to _____ banks can be _____ and hide the time to access the row and select the column
- Consecutive accesses within _____ (to different rows) exposes the access latency



Access 1 maps to bank 1 while access 2a maps to bank 2 allowing parallel access. However, access 2b immediately follows and maps to bank 2 causing a delay.

Programming Considerations

- For memory configuration given earlier, accesses to the same bank but different row occur on an 32KB boundary
- Now consider a matrix multiply of 8K x 8K integer matrices (i.e. 32KB x 32KB)
- In code below...m2[0][0] @ 0x10010000 while m2[1][0] @ 0x10018000

Unused	Rank	Row	Bank	Col.	Unused
A31,A30	A29	A28...A15	A14,A13	A12...A3	A2..A0
00	0	1 0000 0000 0001 0	00	0000000000	000
00	0	1 0000 0000 0001 1	00	0000000000	000

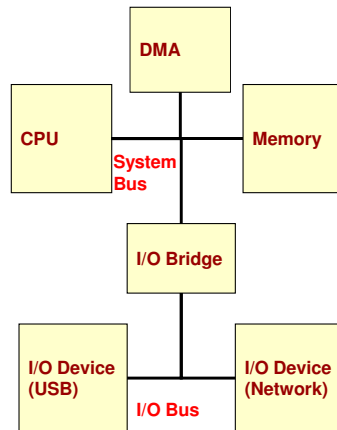

```

int m1[8192][8192], m2[8192][8192], result[8192][8192];
int i, j, k;
...
for(i=0; i < 8192; i++){
  for(j=0; j < 8192; j++){
    result[i][j]=0;
    for(k=0; k < 8192; k++){
      result[i][j] += matrix1[i][k] * matrix2[k][j];
    } } }
    
```

DMA & ENDIAN-NESS

Direct Memory Access (DMA)

- Large buffers of data often need to be copied between:
 - _____ (video data, network traffic, etc.)
 - _____ (OS space to user app. space)
- DMA devices are small hardware devices that copy data from a source to destination freeing the processor to do _____



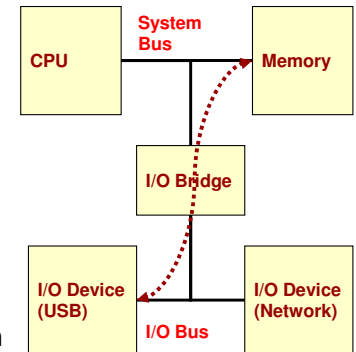
Data Transfer w/o DMA

- Without DMA, processor would have to move data using a loop
- Move 16Kwords pointed to by (\$s1) to (\$s2)

```

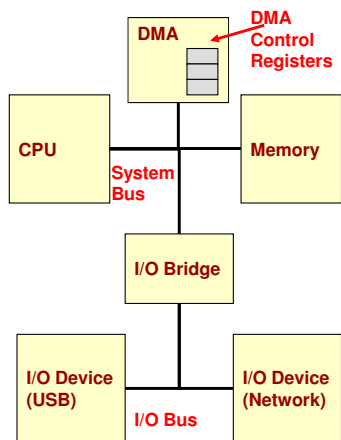
li    $t0, 16384
AGAIN: lw  $t1, 0($s1)
      sw  $t1, 0($s2)
      addi $s1, $s1, 4
      addi $s2, $s2, 4
      subi $t0, $t0, 1
      bne $t0, $zero, AGAIN
    
```

- Processor wastes valuable execution time moving data



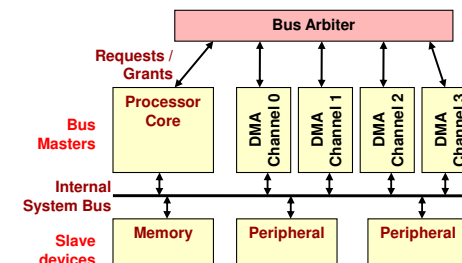
Data Transfer w/ DMA

- Processor sets values in DMA control registers
 - _____ Address
 - _____ Address
 - _____
 - Control & Status (Start, Stop, Interrupt on Completion, etc.)
- DMA becomes "_____"
(controls system bus to generate reads and writes) while processor is free to execute other code
 - Small problem: _____
 - Hopefully, data & code needed by the CPU will reside in _____



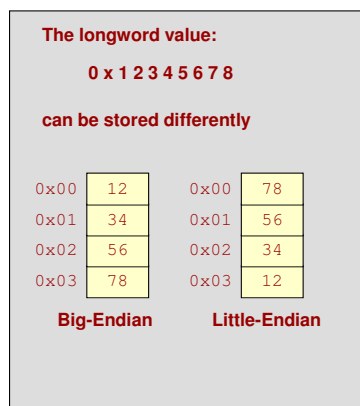
DMA Engines

- Systems usually have multiple DMA engines/channels
- Each can be configured to be started/controlled by the processor or by certain I/O peripherals
 - Network or other peripherals can initiate DMA's on their behalf
- Bus arbiter assigns control of the bus
 - Usually winning requestor has control of the bus until it relinquishes it (turns off its request signal)



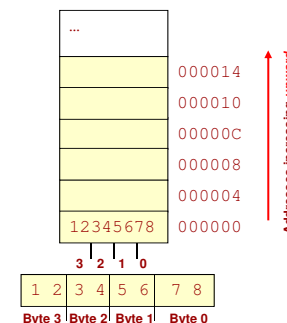
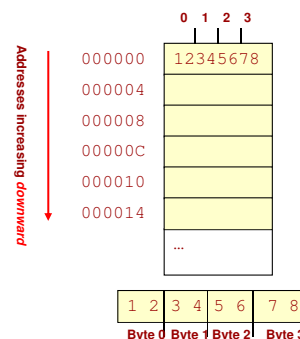
Endian-ness

- Endian-ness** refers to the two alternate methods of _____
_____ in a larger unit (word, long, etc.)
 - Big-Endian
 - PPC, Sparc
 - MS byte is put at the starting address
 - Little-Endian
 - used by Intel processors / PCI bus
 - LS byte is put at the starting address



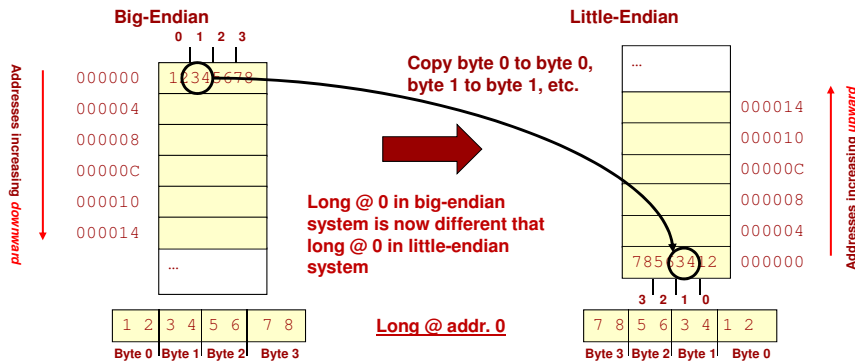
Big-endian vs. Little-endian

- Big-endian**
 - makes sense if you view your memory as starting at the top-left and addresses increasing as you go down
- Little-endian**
 - makes sense if you view your memory as starting at the bottom-right and addresses increasing as you go up



Big-endian vs. Little-endian

- Issues arise when transferring data between different systems
 - Byte-wise copy of data from big-endian system to little-endian system
 - Major issue in networks (little-endian computer => big-endian computer) and even within a single computer (System memory => Peripheral (PCI) device)

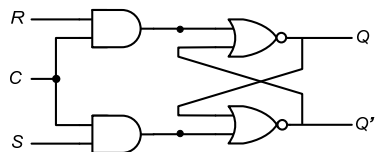
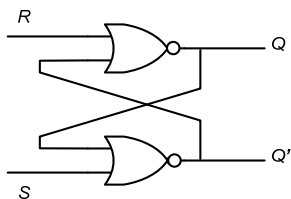


Sequential Cells

BACKUP

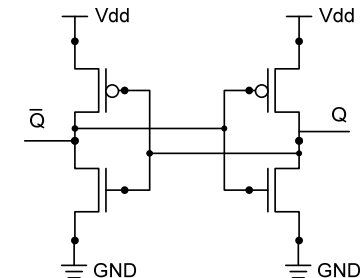
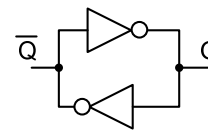
Sequential Cell Review

- We've seen how to build basic combinational gates but what about sequential circuits
- We can build the bistables and latches we've seen at the gate level with direct CMOS substitutions
 - Replace each NOR or AND gate with it's CMOS transistor level equivalent



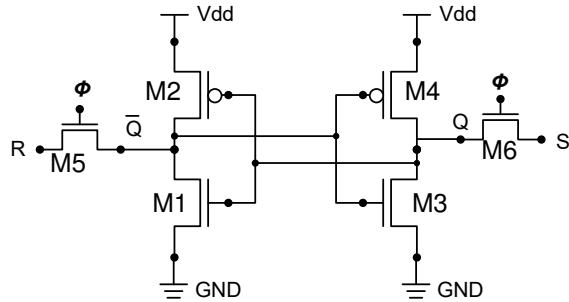
Sequential Cell Review

- We can also take advantage of our circuit level understanding of transistors, capacitance, and sizing to build the bistables and latches in other (possibly more efficient) ways
- The simplest sequential cell is just a feedback loop of inverters
 - Problem...how do we change the value, Q?



An SR-Latch

- We can use pass transistors to pull the output Q or Q' to a new value
 - Note: ϕ is the CLK signals



An SR-Latch

- Consider the case when $Q(t=0)=0$ and we then apply the set input
 - After a short time the pass transistor connected to S and the pull down transistor connected from Q to GND will be in linear mode and form a voltage divider
 - Some analysis will show us that we must make $(W/L)_{M6} > (W/L)_{M3}$ by some appropriate factor to get Q to switch

