

Spiral 2-4

Function synthesis with:
Muxes (Shannon's Theorem)
Memories

Learning Outcomes

- I can implement logic for any truth table by using Shannon's theorem to decompose the function to create two smaller functions and a 2-to-1 mux
 - I can recursively apply Shannon's theorem k times to decompose any size truth table to arrive at 2^k smaller functions and a 2^k -to-1 mux
- I can implement logic for any truth table by using a memory as a look-up table
 - I understand how to determine the necessary dimensions of the memory
 - I understand how to reinterpret input combinations as address inputs to determine the correct row to place the desired output

Function Synthesis Techniques

- Given a combination function (i.e. truth table or other description) what methods can we use to arrive at a circuit?
 - Karnaugh maps
 - Sum of minterms / Produce of maxterms
 - Neither of these scale well to larger number of inputs
- Now we will see a few others

| X | Y | Z | P |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 1 |

Primes between
0-7

Implementing functions with muxes

SHANNON'S THEOREM

Simplify This

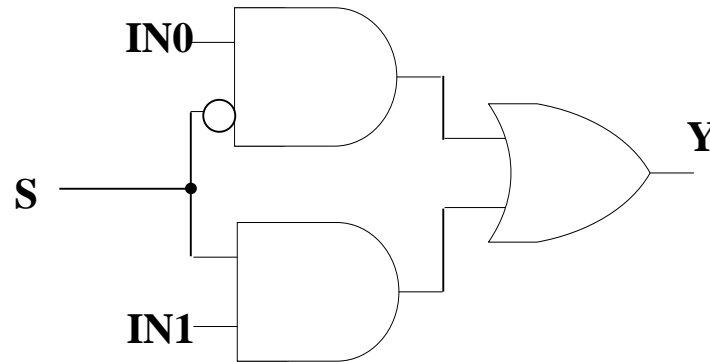
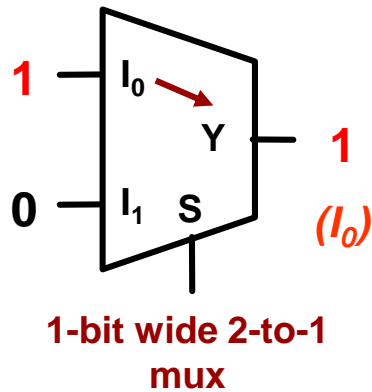
- Given $F(x,y,z) = x'yz + y'z'$,
simplify $F(0,y,z) =$

then simplify $F(1,y,z) =$

- Given $G(a,b,c,d) = bd' + ab'cd + ac'd'$
 $G(1,1,c,d) =$

2-to-1 Mux: Another View

Old Views:

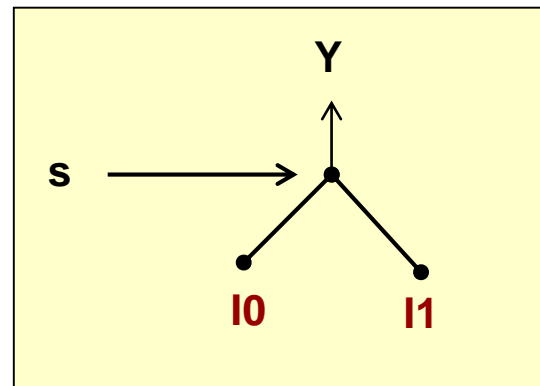


```

if(s==0)
    Y = IN0
else
    Y = IN1
    
```

New View:

We can show the function of a 2-to-1 mux as a splitter where the variable 's' decides which input passes upwards



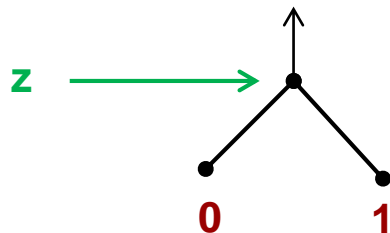
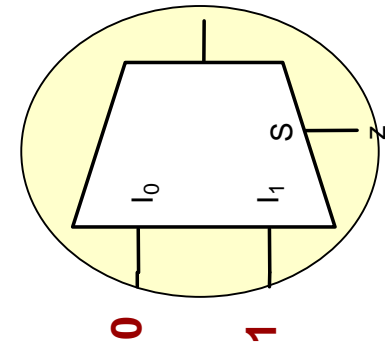
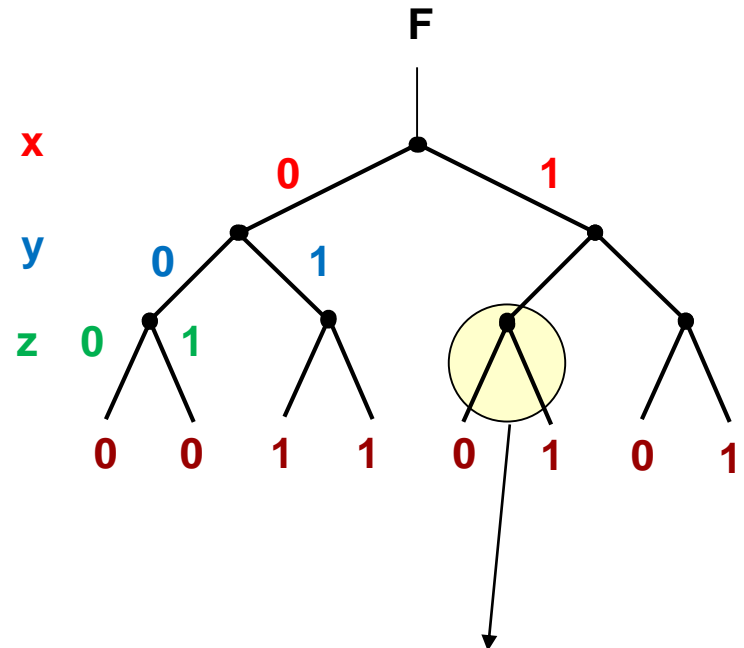
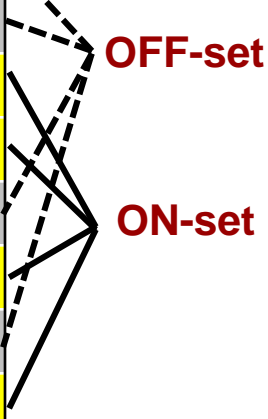
3-bit Prime Number Function

| X | Y | Z | P |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 1 |

Primes between 0-7

| X | Y | Z | P |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 1 |

Truth Table



if(z==0)
 output 0
 else
 output 1

Function Implementation w/ Muxes

- Implementing a function using muxes relies is based on Shannon's expansion theorem which states:
 - $F(X_1, X_2, \dots, X_n) = X_1' \cdot F(0, X_2, \dots, X_n) + X_1 \cdot F(1, X_2, \dots, X_n)$
 - X_1 can be pulled out of F if we substitute an appropriate constant and qualify it with X_1' or X_1
- Now recall a 2-to-1 mux can be built as:
 - $F = S' \cdot I_0 + S \cdot I_1$
 - Comparing the two equations, Shannon's theorem says we can use X_1 as our select bit to a 2-to-1 mux with $F(0, X_2, \dots, X_n)$ as input 0 of our mux and $F(1, X_2, \dots, X_n)$ as input 1

Binary Decision Trees & Muxes

| X | Y | Z | F |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| | 0 | 1 | 0 |
| | 1 | 0 | 1 |
| | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| | 0 | 1 | 1 |
| | 1 | 1 | 1 |

$F(x,y,z)$

| Y | Z | F |
|---|---|---|
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

$F(0,y,z)$

| Y | Z | F |
|---|---|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |

$F(1,y,z)$

| Z | F |
|---|---|
| 0 | 0 |
| 1 | 0 |

$F(0,0,z)$

| Z | F |
|---|---|
| 0 | 1 |
| 1 | 1 |

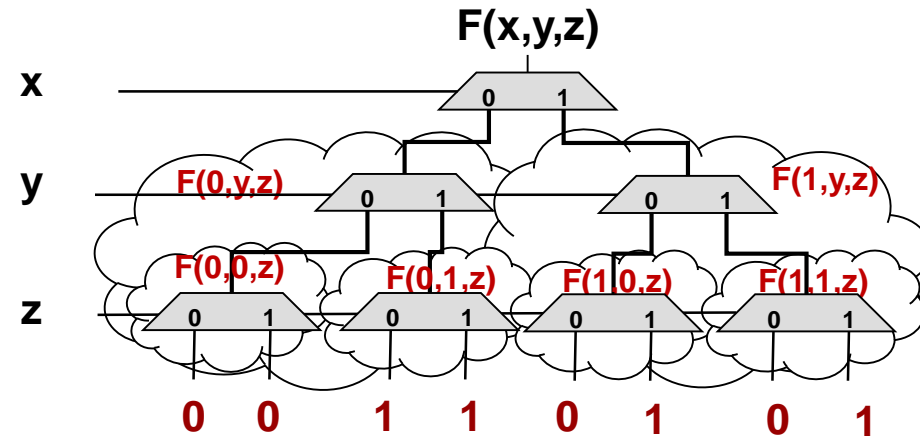
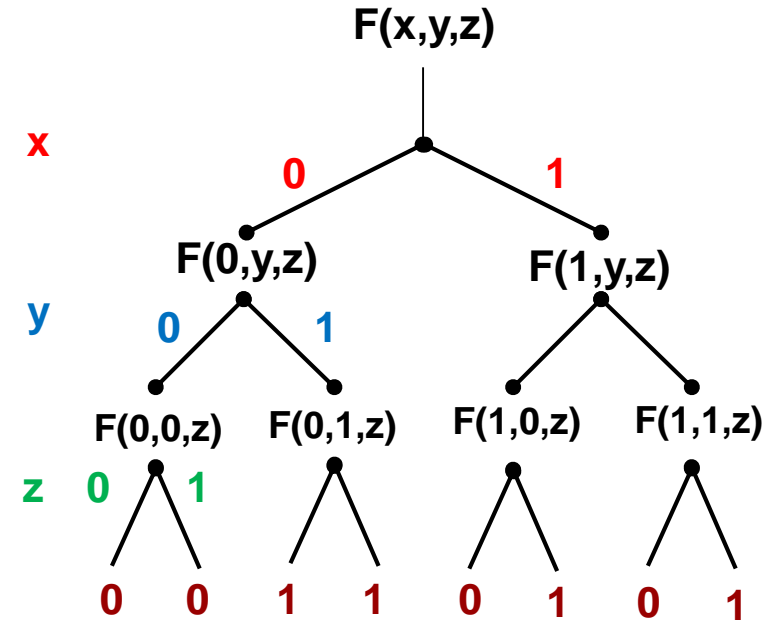
$F(0,1,z)$

| Z | F |
|---|---|
| 0 | 0 |
| 1 | 1 |

$F(1,0,z)$

| Z | F |
|---|---|
| 0 | 0 |
| 1 | 1 |

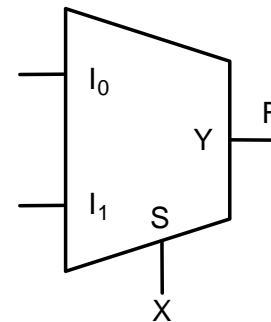
$F(1,1,z)$



Splitting on X

- We can use smaller muxes by breaking the truth table into fewer disjoint sets
 - This increases the amount of logic at the inputs though**
- Break the truth table into groups based on some number (**k**) of MSB's
- For each group, describe F as a function of the **n-k LSB's**

| X | Y | Z | F |
|----------|---|---|----------|
| 0 | 0 | 0 | 0 |
| | 0 | 1 | 1 |
| | 1 | 0 | 1 |
| | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 |
| | 0 | 1 | 1 |
| | 1 | 0 | 0 |
| | 1 | 1 | 1 |



Put the k MSB's on the selects

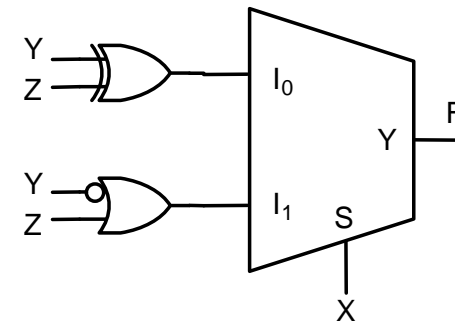
Splitting on X

- We can use smaller muxes by breaking the truth table into fewer disjoint sets
 - This increases the amount of logic at the inputs though
- Break the truth table into groups based on some number (k) of MSB's
- For each group, describe F as a function of the $n-k$ LSB's

| X | Y | Z | F |
|----------|---|---|----------|
| 0 | 0 | 0 | 0 |
| | 0 | 1 | 1 |
| | 1 | 0 | 1 |
| | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 |
| | 0 | 1 | 1 |
| | 1 | 0 | 0 |
| | 1 | 1 | 1 |

**$y \text{ xor } z$
 $(y'z + yz')$**

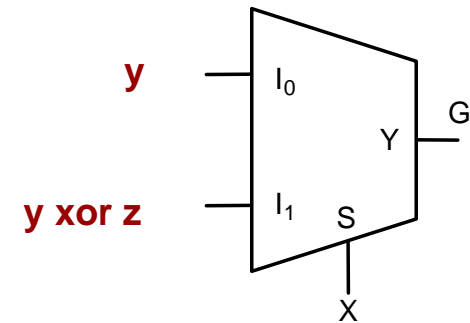
$(y' + z)$



Put the k MSB's on the selects

Implement G

| X | Y | Z | G |
|----------|---|---|----------|
| 0 | 0 | 0 | 0 |
| | 0 | 1 | 0 |
| | 1 | 0 | 1 |
| | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| | 0 | 1 | 1 |
| | 1 | 0 | 1 |
| | 1 | 1 | 0 |



Shannon's Theorem

- $F(X_1, X_2, \dots, X_n) = X_1' \cdot F(0, X_2, \dots, X_n) + X_1 \cdot F(1, X_2, \dots, X_n)$
- Now recall a 2-to-1 mux can be built as:
 - $F = S' \cdot I_0 + S \cdot I_1$
 - Comparing the two equations, Shannon's theorem says we can use X_1 as our select bit to a 2-to-1 mux with $F(0, X_2, \dots, X_n)$ as input 0 of our mux and $F(1, X_2, \dots, X_n)$ as input 1
- We can recursively apply Shannon's theorem to pull out more variables:
 - $F(X_1, X_2, \dots, X_n) =$
 $X_1' X_2' \cdot F(0, 0, \dots, X_n) + X_1' X_2 \cdot F(0, 1, \dots, X_n) +$
 $X_1 X_2' \cdot F(1, 0, \dots, X_n) + X_1 X_2 \cdot F(1, 1, \dots, X_n) +$

Additional Logic

- Muxes allow us to break a function into some number of smaller, disjoint functions
- Use MSB's to choose which small function we want
- By including the use of inverters we can use a mux with $n-1$ select bits (given a function of n -var's)
- Break the truth table into groups of 2 rows
- For each group, put F in terms of: $z, z', 0, \text{ or } 1$

| X | Y | Z | F | |
|----------|----------|---|----------|-----------|
| 0 | 0 | 0 | 0 | z |
| | | 1 | 1 | |
| 0 | 1 | 0 | 1 | z' |
| | | 1 | 0 | |
| 1 | 0 | 0 | 1 | 1 |
| | | 1 | 1 | |
| 1 | 1 | 0 | 0 | z |
| | | 1 | 1 | |

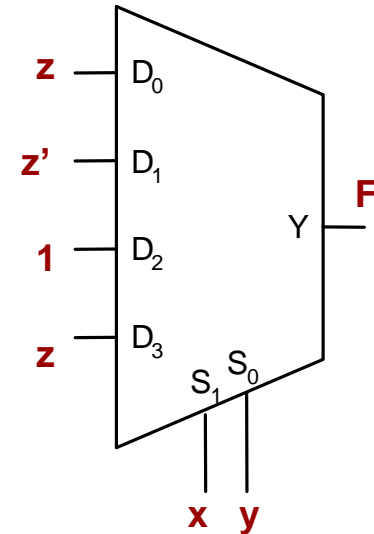
$F(x,y,z)$ can be broken into several disjoint functions

$F_0(z)$

$F_1(z)$

$F_2(z)$

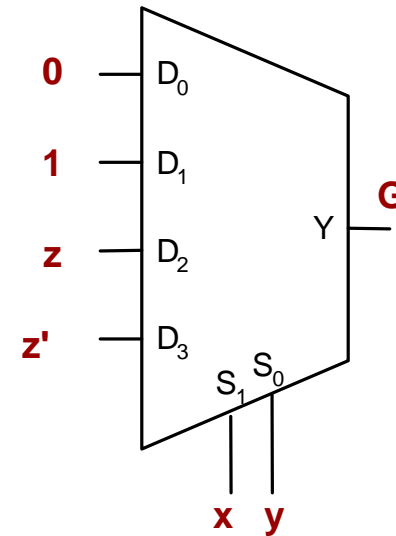
$F_3(z)$



Put the $n-1$ MSB's on the selects

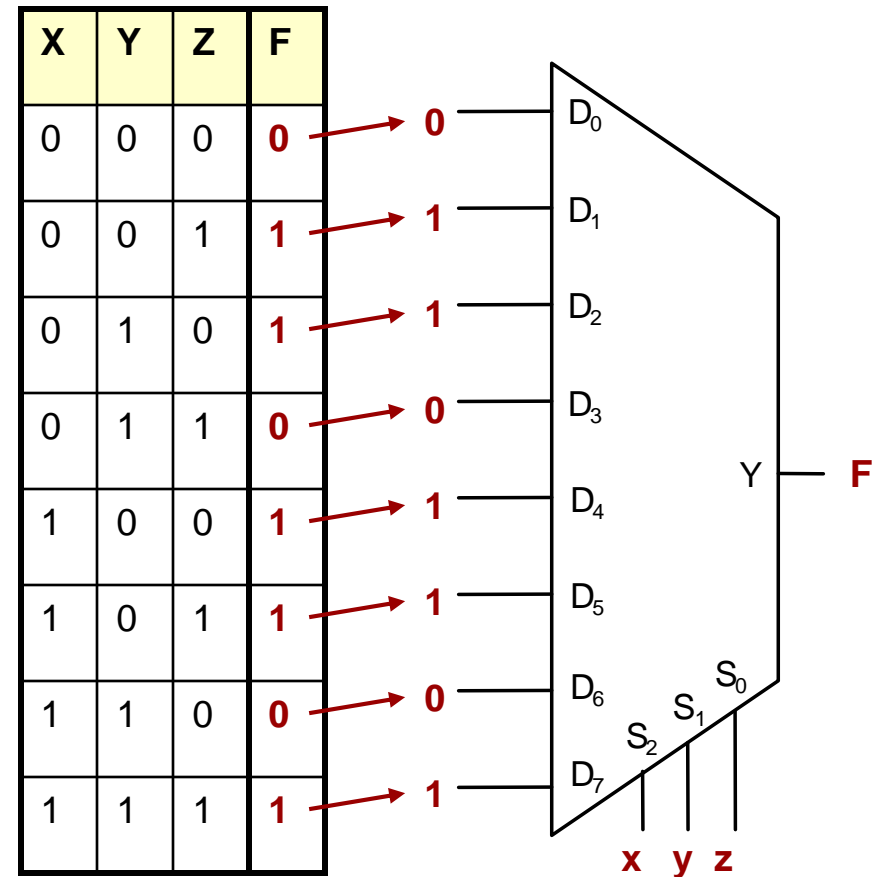
More Practice

| X | Y | Z | G |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| | | 1 | 0 |
| 0 | 1 | 0 | 1 |
| | | 1 | 1 |
| 1 | 0 | 0 | 0 |
| | | 1 | 1 |
| 1 | 1 | 0 | 1 |
| | | 1 | 0 |



As Far as We like

- We can take this tactic all the way down and use ONLY a mux to implement any function
- Connect the input variables to the select bits of the mux
- The output of the mux is the output of the function
- Whatever the output should be for each input value, attach that to the input of the mux

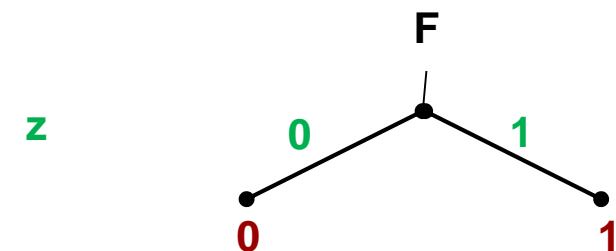
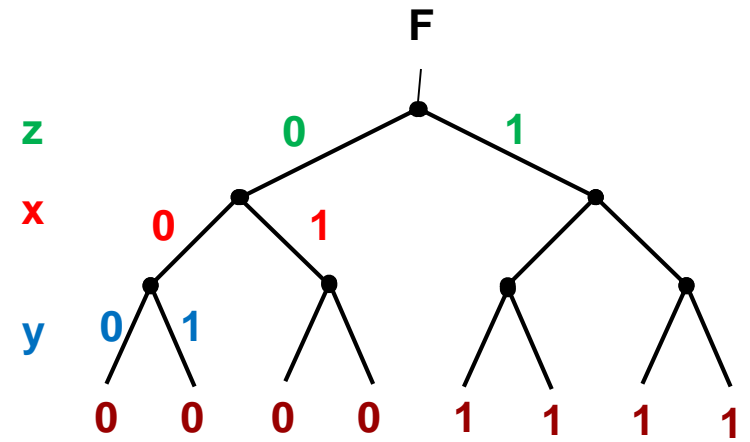
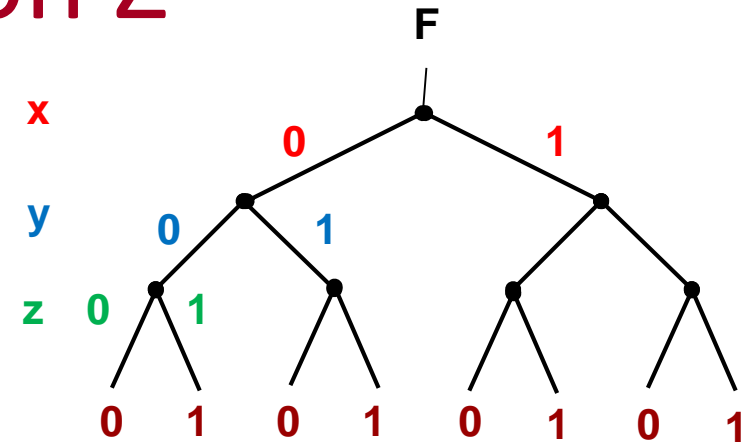


Splitting on Z

- We can always rearrange our variables if it helps make the function simpler to implement

| X | Y | Z | F |
|----------|---|---|----------|
| 0 | 0 | 0 | 0 |
| | 0 | 1 | 1 |
| | 1 | 0 | 0 |
| | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| | 0 | 1 | 1 |
| | 1 | 0 | 0 |
| | 1 | 1 | 1 |

| Z | X | Y | F |
|----------|---|---|----------|
| 0 | 0 | 0 | 0 |
| | 0 | 1 | 0 |
| | 1 | 0 | 0 |
| | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 |
| | 0 | 1 | 1 |
| | 1 | 0 | 1 |
| | 1 | 1 | 1 |

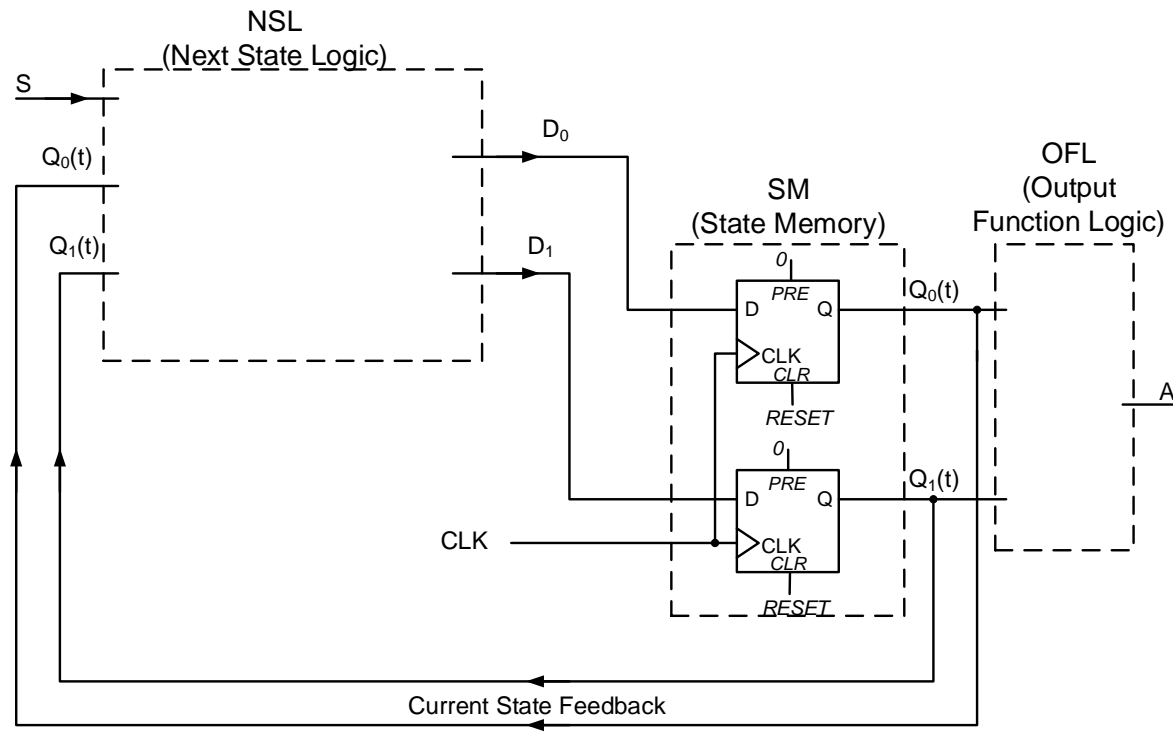


Implementing Logic Functions

- We can use muxes to implement any arbitrary logic function
 - Choose one variable to split the large function into two smaller functions: $f(0, x_2, x_3, \dots)$ and $f(1, x_2, x_3, \dots)$
 - A 2-to-1 mux will produce the output bit and the chosen "split" variable will be the select
 - Implement $f(0, x_2, x_3, \dots)$ using any known method and connect it to input 0 of the 2-to-1 mux
 - Implement $f(1, x_2, x_3, \dots)$ using any known method and connect it to input 1 of the 2-to-1 mux

Implementing an Initial State

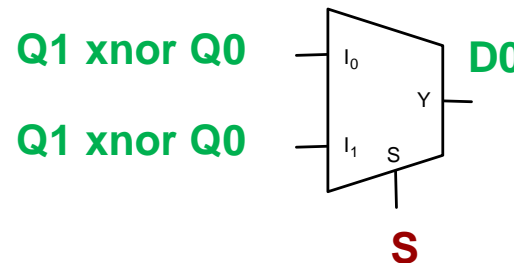
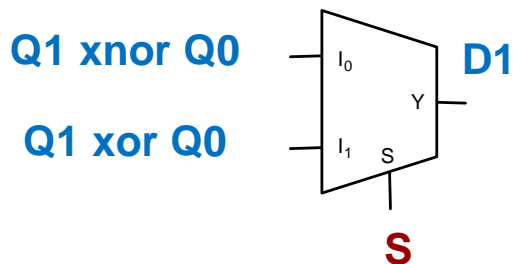
- Since the NSL is just a combinational function of the current state and inputs, we can use Shannon's theorem (i.e. muxes) to find an implementation rather than K-Maps



Example 1

- Implement D1 & D0 using 2-to-1 muxes with S as the select

| Current State | | | Next State | | | | | | Output |
|---------------|----------------|----------------|------------|------------|------------|-------|-------------|-------------|--------|
| | | | S = 0 | | | S = 1 | | | |
| State | Q ₁ | Q ₀ | State | Q1*= D1 | Q0*= D0 | State | Q1*= =D1 | Q0*= =D0 | A |
| G01 | 0 | 0 | G00 | 1 | 1 | G10 | 0 | 1 | 1 |
| G10 | 0 | 1 | G01 | 0 | 0 | G11 | 1 | 0 | 1 |
| G00 | 1 | 1 | G00 | 1 | 1 | G10 | 0 | 1 | 0 |
| G11 | 1 | 0 | G01 | 0 | 0 | G11 | 1 | 0 | 0 |

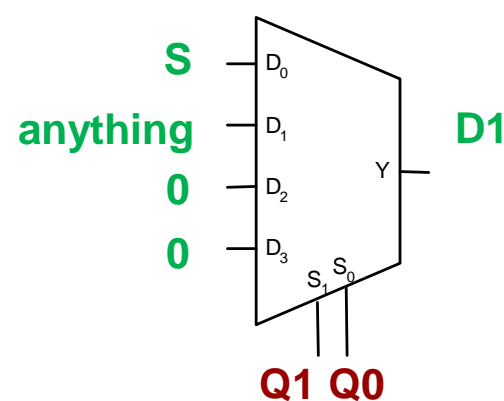
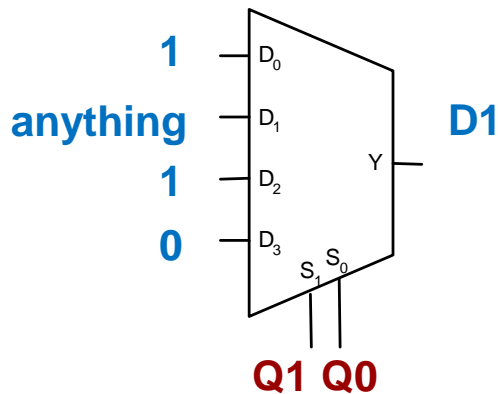


D0 = Q1 xnor Q0
(Since both inputs are xnor, we don't need the mux)

Example 2

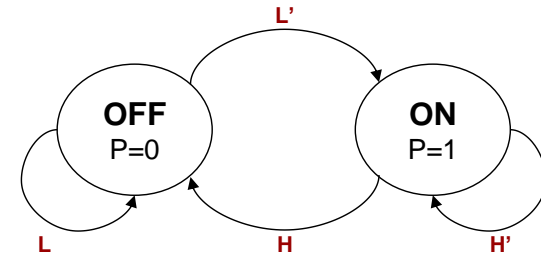
- Implement D1 and D0 using (2) 4-to-1 muxes with Q1, Q0 as the selects

| Current State | | | Next State | | | | | | Output | | |
|---------------|----------------|----------------|------------|------------------|------------------|-------|------------------|------------------|--------|-----|-----|
| | | | S = 0 | | | S = 1 | | | | | |
| State | Q ₁ | Q ₀ | State | Q ₁ * | Q ₀ * | State | Q ₁ * | Q ₀ * | SSG | MTG | MSG |
| SS | 0 | 0 | MS | 1 | 0 | MT | 1 | 1 | 1 | 0 | 0 |
| N/A | 0 | 1 | X | d | d | X | d | d | d | d | d |
| MT | 1 | 1 | MS | 1 | 0 | MS | 1 | 0 | 0 | 1 | 0 |
| MS | 1 | 0 | SS | 0 | 0 | SS | 0 | 0 | 0 | 0 | 1 |



Example 3

- Implement D using a mux

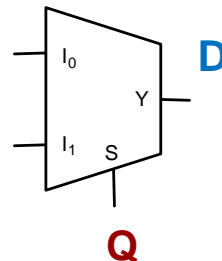


| Current State | | Next State | | | | | | | |
|---------------|---|------------|----|----------|----|----------|----|----------|----|
| | | HL = 0 0 | | HL = 0 1 | | HL = 1 1 | | HL = 1 0 | |
| Symbol | Q | Sym. | Q* | Sym. | Q* | Sym. | Q* | Sym. | Q* |
| OFF | 0 | ON | 1 | OFF | 0 | OFF | 0 | X | d |
| ON | 1 | ON | 1 | ON | 1 | OFF | 0 | X | d |

Note: The State Value, Q forms the Pump output (i.e. 1 when we want the pump to be on and 0 otherwise)

Due to don't care:
Option 1: H'L'
Option 2: L'

Option 1: H'
Option 2: H'+L'

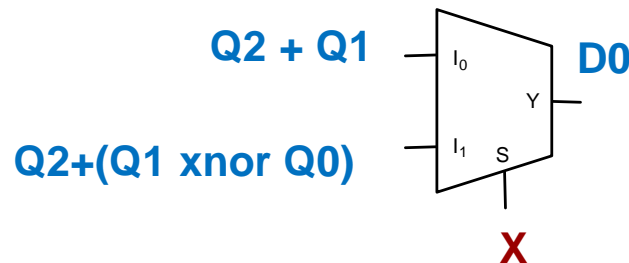


Example 4

Do a K-Map for each column separately since the mux splits them

- Implement D0 using a mux.

| Current State | | | | Next State | | | | | | | | Output |
|---------------|----|----|----|------------|----|----|----|--------|----|----|----|--------|
| | | | | X = 0 | | | | X = 1 | | | | |
| State | Q2 | Q1 | Q0 | State* | D2 | D1 | D0 | State* | D2 | D1 | D0 | Z |
| Sinit | 0 | 0 | 0 | Sinit | 0 | 0 | 0 | S1 | 0 | 1 | 1 | 0 |
| S10 | 0 | 0 | 1 | Sinit | 0 | 0 | 0 | S101 | 0 | 1 | 0 | 0 |
| S1 | 0 | 1 | 1 | S10 | 0 | 0 | 1 | S1 | 0 | 1 | 1 | 0 |
| S101 | 0 | 1 | 0 | S10 | 0 | 0 | 1 | S1011 | 1 | 1 | 0 | 0 |
| S1011 | 1 | 1 | 0 | S10 | 0 | 0 | 1 | S1 | 0 | 1 | 1 | 1 |



Summary

- Shannon's theorem allows us to decompose an ARBITRARILY large function into many smaller functions
- This allows a method that can scale for a function with many variables
- It is at the heart of many computer algorithms that will find logic implementation given high-level descriptions of a function

Using a LookUp-Table to implement a function

MEMORIES

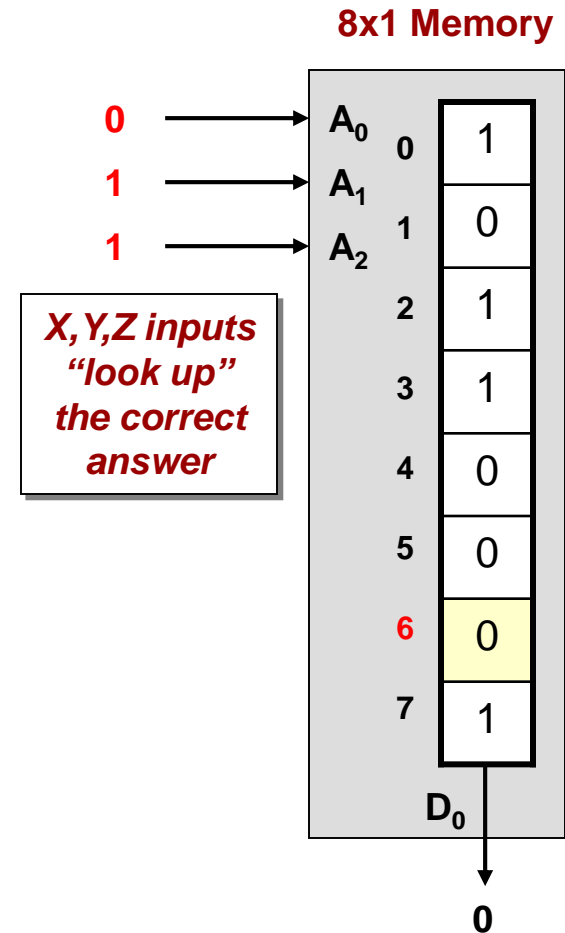
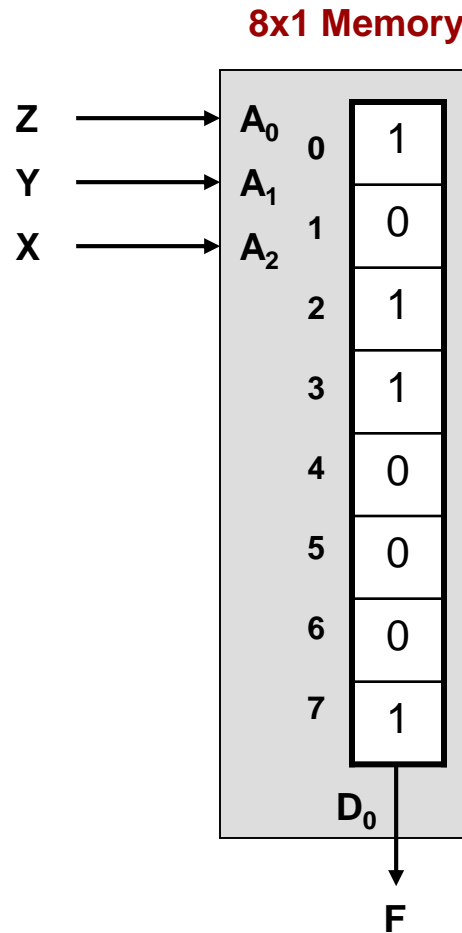
Memories as Look-Up Tables

- One major application of memories in digital design is to use them as LUT's (Look-Up Tables) to implement logic functions
- Given a logic function use a memory to hold all the possible answers and feed the inputs of the function to the address inputs to look-up the answer

Implementing Functions w/ Memories

| X | Y | Z | F |
|---|---|---|---|
| 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 1 |

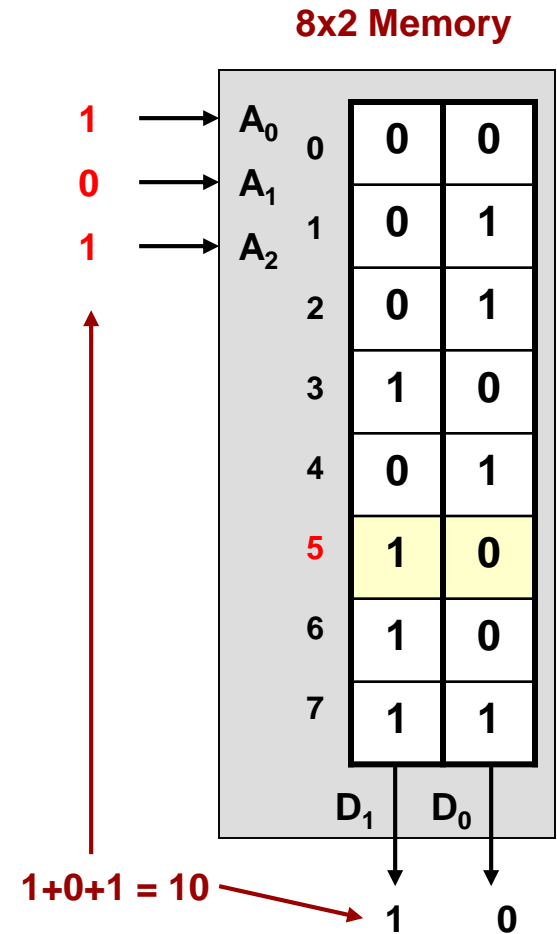
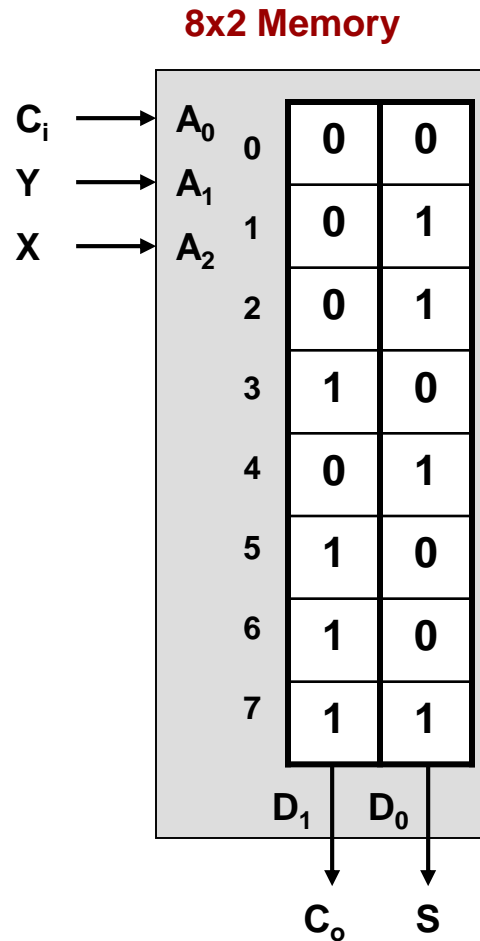
Arbitrary
Logic
Function



Implementing Functions w/ Memories

| X | Y | C _i | C _o | S |
|---|---|----------------|----------------|---|
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 | 1 |
| 0 | 1 | 0 | 0 | 1 |
| 0 | 1 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 | 1 |
| 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 0 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 |

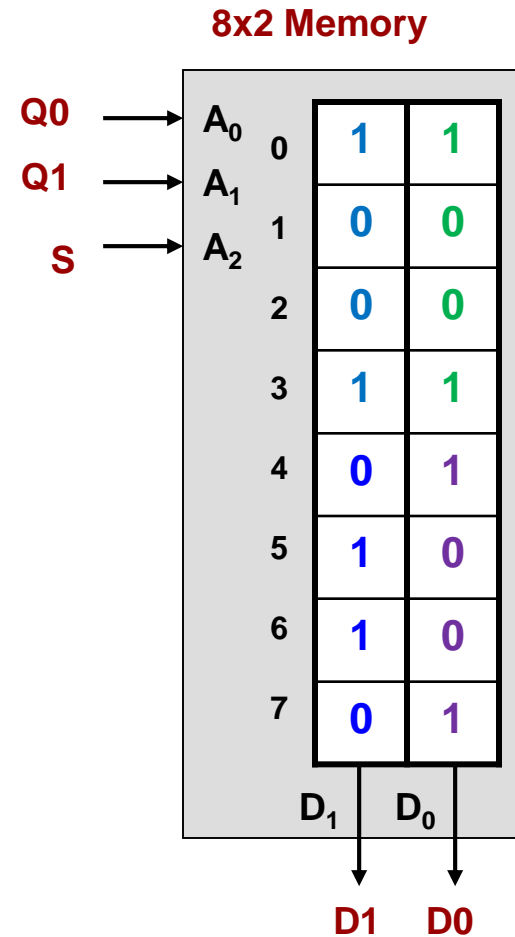
Full Adder



Example 1

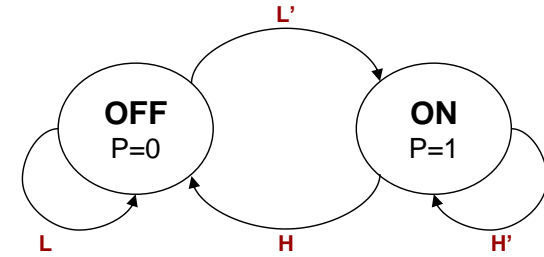
- Implement D1 & D0 using a memory

| Current State | | | Next State | | | | | |
|---------------|----------------|----------------|------------|-----|-----|-------|-----|-----|
| | | | S = 0 | | | S = 1 | | |
| State | Q ₁ | Q ₀ | State | Q1* | Q0* | State | Q1* | Q0* |
| G01 | 0 | 0 | G00 | 1 | 1 | G10 | 0 | 1 |
| G10 | 0 | 1 | G01 | 0 | 0 | G11 | 1 | 0 |
| G00 | 1 | 1 | G00 | 1 | 1 | G10 | 0 | 1 |
| G11 | 1 | 0 | G01 | 0 | 0 | G11 | 1 | 0 |

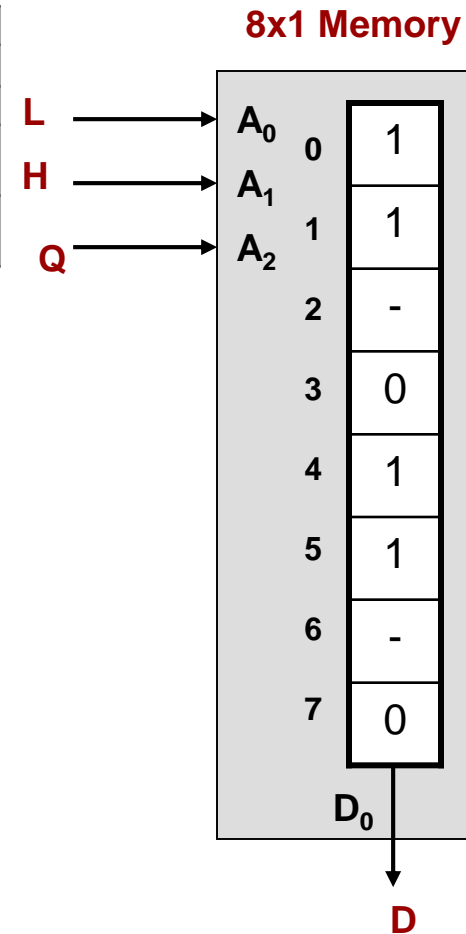


Example 2

- Implement D using a memory



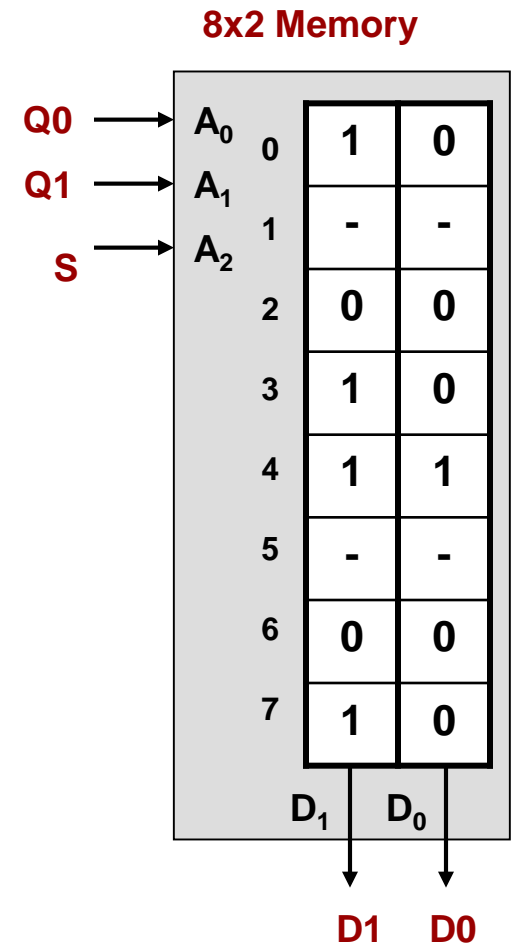
| Current State | | Next State | | | | | | | |
|---------------|---|------------|----|-------|----|-------|----|-------|----|
| | | HL=00 | | HL=01 | | HL=11 | | HL=10 | |
| Symbol | Q | Sym. | Q* | Sym. | Q* | Sym. | Q* | Sym. | Q* |
| OFF | 0 | ON | 1 | OFF | 0 | OFF | 0 | X | d |
| ON | 1 | ON | 1 | ON | 1 | OFF | 0 | X | d |



Example 3

- Implement D1 and D0 using a memory

| Current State | | | Next State | | | | | | Output | | |
|---------------|----------------|----------------|------------|------------------|------------------|-------|------------------|------------------|--------|-----|-----|
| | | | S = 0 | | | S = 1 | | | | | |
| State | Q ₁ | Q ₀ | State | Q ₁ * | Q ₀ * | State | Q ₁ * | Q ₀ * | SSG | MTG | MSG |
| SS | 0 | 0 | MS | 1 | 0 | MT | 1 | 1 | 1 | 0 | 0 |
| N/A | 0 | 1 | X | d | d | X | d | d | d | d | d |
| MT | 1 | 1 | MS | 1 | 0 | MS | 1 | 0 | 0 | 1 | 0 |
| MS | 1 | 0 | SS | 0 | 0 | SS | 0 | 0 | 0 | 0 | 1 |



4x4 Multiplier Example

Determine the dimensions of the memory that would be necessary to implement a 4x4-bit unsigned multiplier with inputs $X[3:0]$ and $Y[3:0]$ and outputs $P[?:0]$
(Question: How many bits are needed for P).

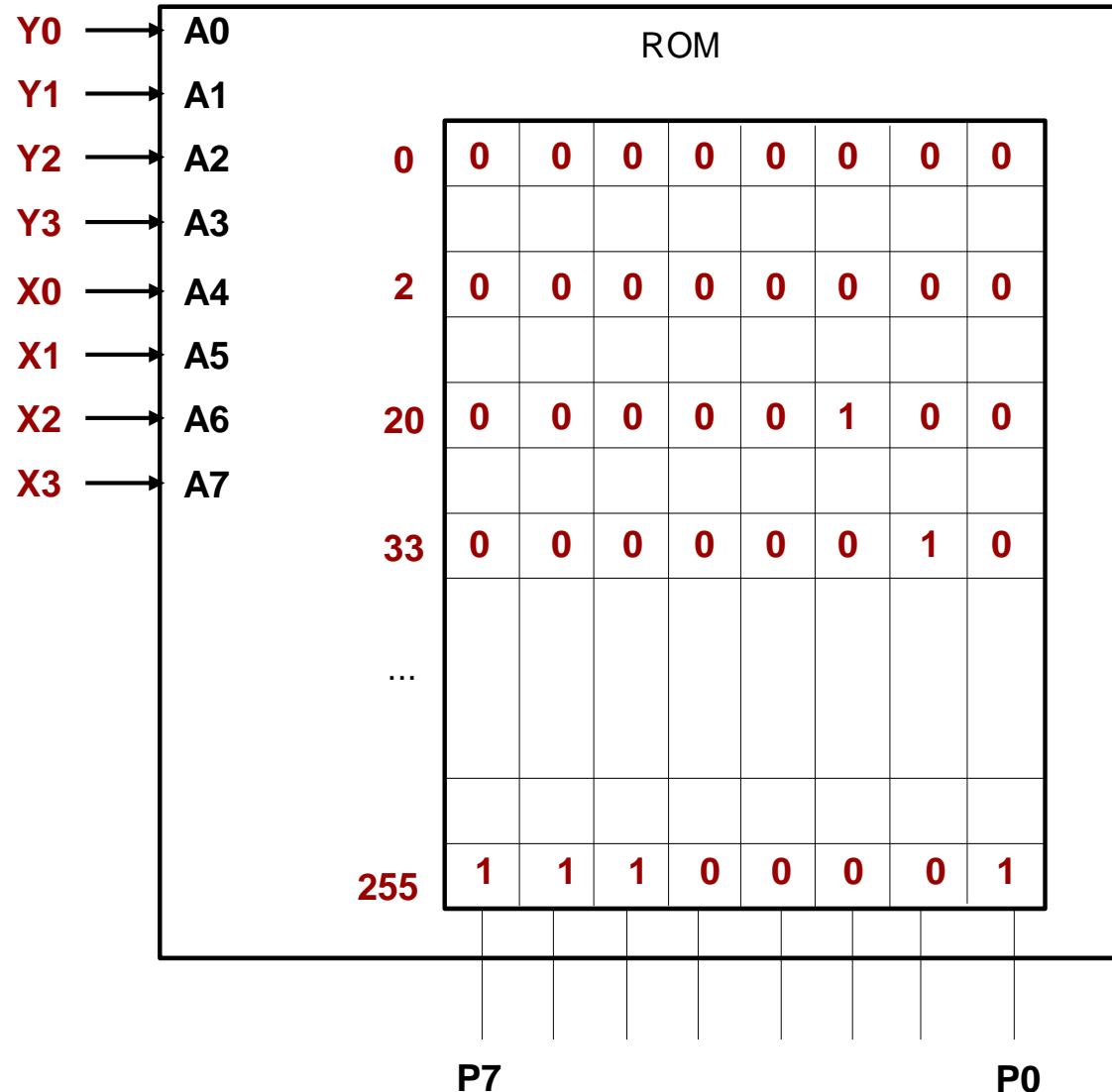
Example:

$$X_3 X_2 X_1 X_0 = 0010$$

$$Y_3 Y_2 Y_1 Y_0 = 0001$$

$$P = X * Y = 2 * 1 = 2$$

$$= 00010$$



Implementing Functions w/ Memories

- To implement a function w/ n -variables and m outputs
- Just place the output truth table values in the memory
- Memory will have dimensions: 2^n rows and m columns
 - Still does not scale terribly well (i.e. n -inputs requires memory w/ 2^n outputs)
 - But it is easy and since we can change the contents of memories it allows us to create "reconfigurable" logic
 - This idea is at the heart of FPGAs